

**DESIGN AND DEVELOPMENT HOMING SYSTEM ON PAYLOAD ROCKET  
VEDA TE 14**

**Hardianto**

Program Studi Teknik Elektro  
Sekolah Tinggi Teknologi Adisutjipto Yogyakarta  
[hardianto2795@gmail.com](mailto:hardianto2795@gmail.com)

**ABSTRACT**

*Nowdays, the aerospace technology development is very fast, especially rocket technology. Inside out of rocket there is a content that called payload. As is this payload a rocket expected to be able to provide an information that can provide some benefit for its users. It is more better that a rocket containing a payload when it has been launched can be in control of payload to be able to return to ground station or at the desired point to save the components and information that has been obtained.*

*In this research its designed a control system on/off, with the result that this device can be controlled remotely, with the control center from ground segment. This system consists of a PC or laptop for the command button converted become a gesture signal the sent through the YS 1020U antenna.*

*The system consists of a motor brushless that moves propeller which can than move the rocket payload. In the process the payload can moving forward and spinning right and left. From this research the telecommand data which sent from pc keyboard on ground station is sent and received well by payload with the result homing process can be done.*

**Keywords:** *Payload Rocket, Payload Control, Arduino Uno, Brushless, Homing.*